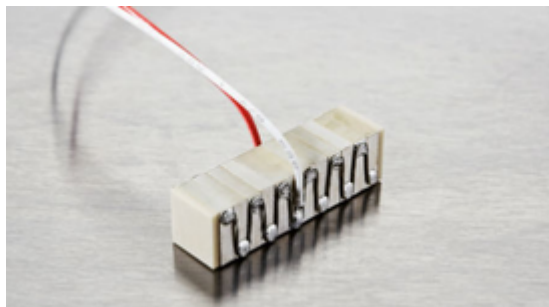


NAC2011-Hxx



Noliac plate stack actuator NAC2011-Hxx (height in mm – Hxx) is based on the multilayer actuator NAC2011 and can be stacked to match your requirements. The standard range of NAC2011-Hxx is produced in a height between 4-20 mm. The plate stack provides a stroke up to 25.25 μm and blocking force up to 168 N depending on the height of the stack.

SPECIFICATIONS

Attributes	Value	Tolerance
Length / outer diameter	2 mm	+0.30/-0.10 mm
Width / inner diameter	2 mm	+0.30/-0.10 mm
Max width / outer diameter max	3.8 mm	
Height	4 — 20 mm	+/-0.2 mm or 1% (whichever is largest)
Operating voltage, max.	150 V	
Free stroke, max.	2.81 — 25.25 μm	+/- 15%
Blocking force, max.	168 N	+/-20%
Capacitance	21-190 nF	+/- 15%
Stiffness	60-7 N/ μm	+/-20%
Maximum operating temperature	150 °C	
Material	NCE51F	
Unloaded resonance frequency	>248 k - 52 k Hz	
Electrodes	Screen-printed Ag and soldered bus wire (option: glued connections)	
Remarks	For stacks higher than 10mm, it may be necessary to add a support within the application in order to avoid bending and buckling during mounting and operation	

Stack options



Your piezo partner

Height

- 4 mm
- 6 mm
- 8 mm
- 10 mm
- 12 mm
- 14 mm
- 16 mm
- 18 mm
- 20 mm

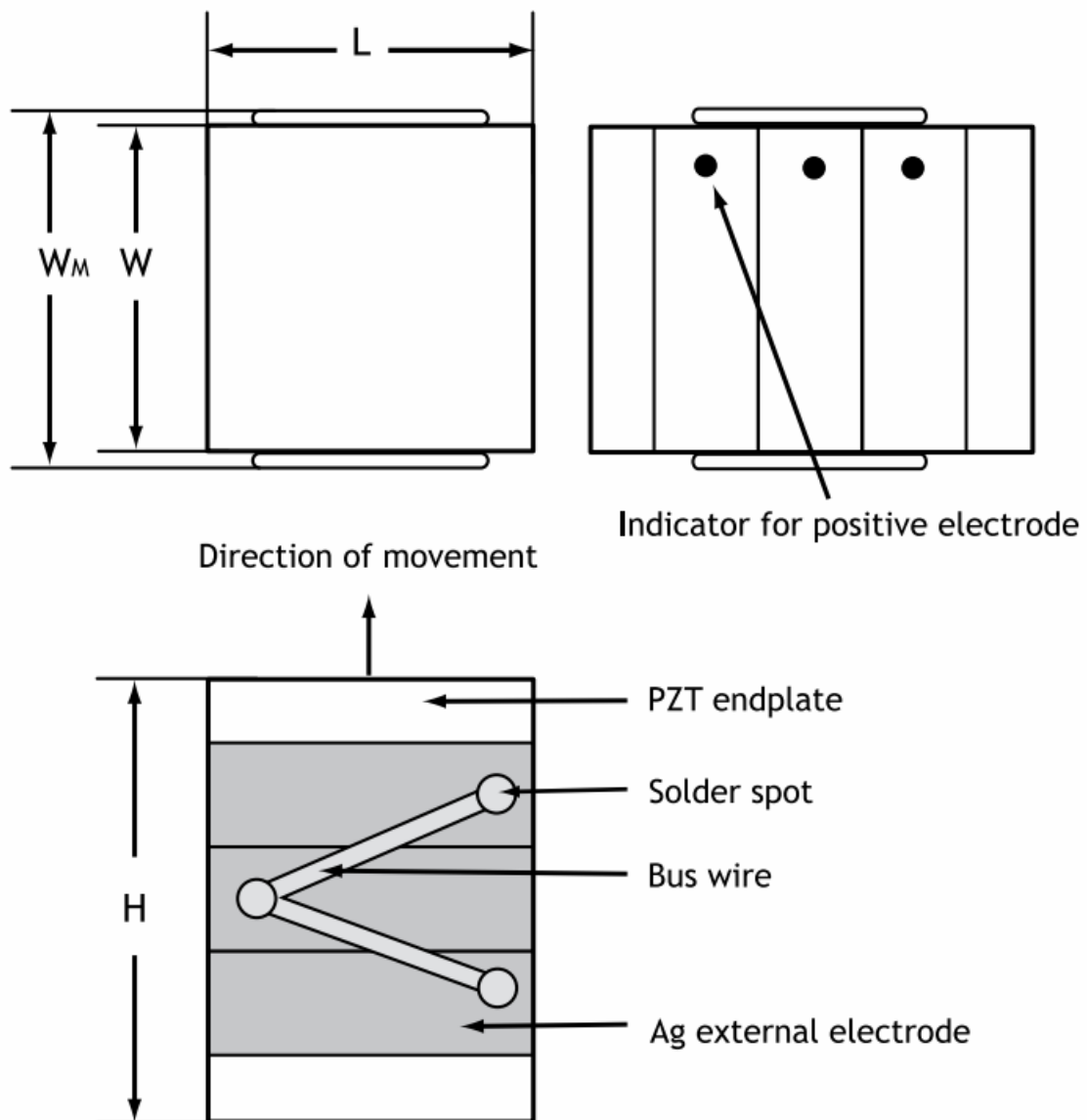
Stroke

- 2.8 µm
- 5.6 µm
- 8.4 µm
- 11.2 µm
- 14 µm
- 16.8 µm
- 19.6 µm
- 22.4 µm
- 25.2 µm

Capacitance

- 20 nF
- 40 nF
- 60 nF
- 90 nF
- 110 nF
- 130 nF
- 150 nF
- 170 nF
- 190 nF

DRAWINGS



MOUNT AND CONNECT

Mounting

The actuators are usually grinded on top and bottom surfaces (perpendicular to the direction of expansion) in order to obtain parallel surfaces for mounting. The actuators may be mounted either by mechanical clamping or gluing.

Avoiding short circuit can either be achieved by:

- Adding Kapton foil on the metallic surfaces.
- Having inactive ceramic plates between the actuator and the metal plate.
- Stacked actuators are manufactured with top and bottom insulating ceramic end-plates.

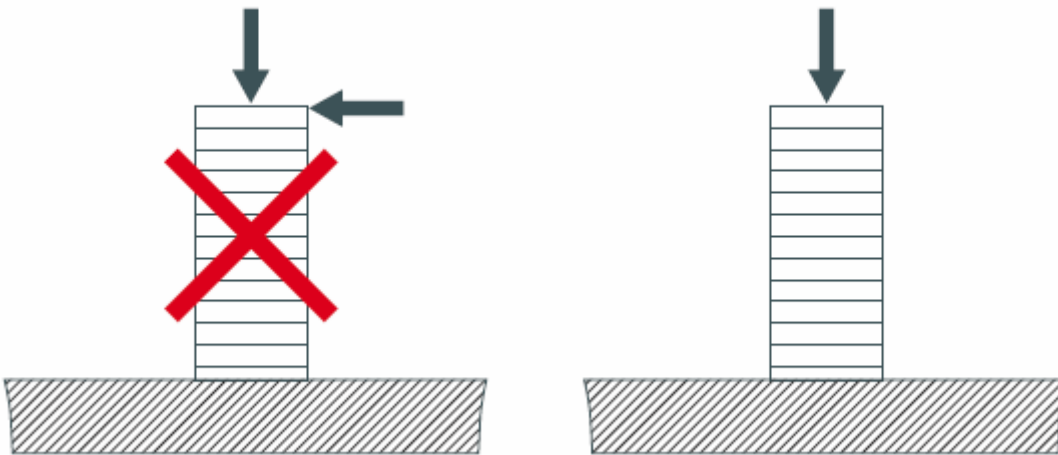
If glued, it is important to ensure a very thin glue line between the actuator and the substrate. It is recommended that a pressure is applied during the curing process.

To avoid significant loss of performance, the mounting of the actuators should avoid mechanical clamping and/or gluing on the side of the actuator.

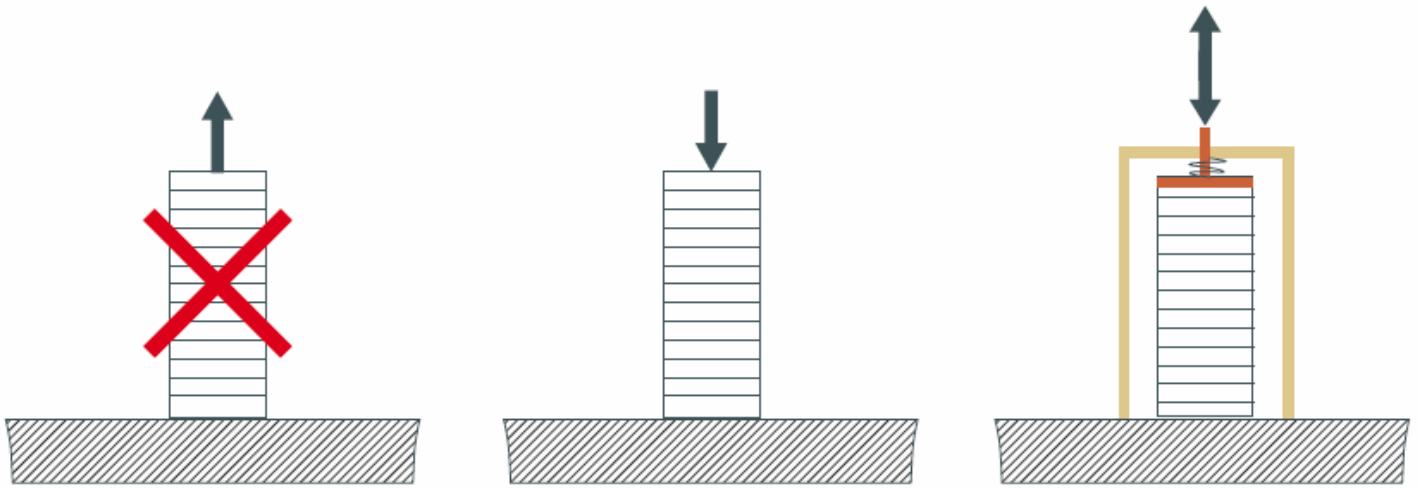
During manufacturing or handling, minor chips on the end-plates can appear. Minor chips cannot be avoided, but such chips do not affect performance.

Electrical connection

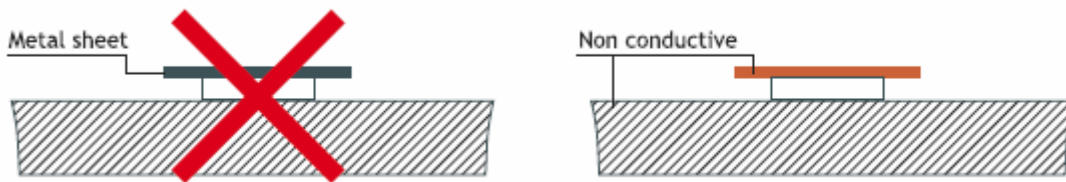
The actuators may only be stressed axially. Tilting and shearing forces must be avoided.



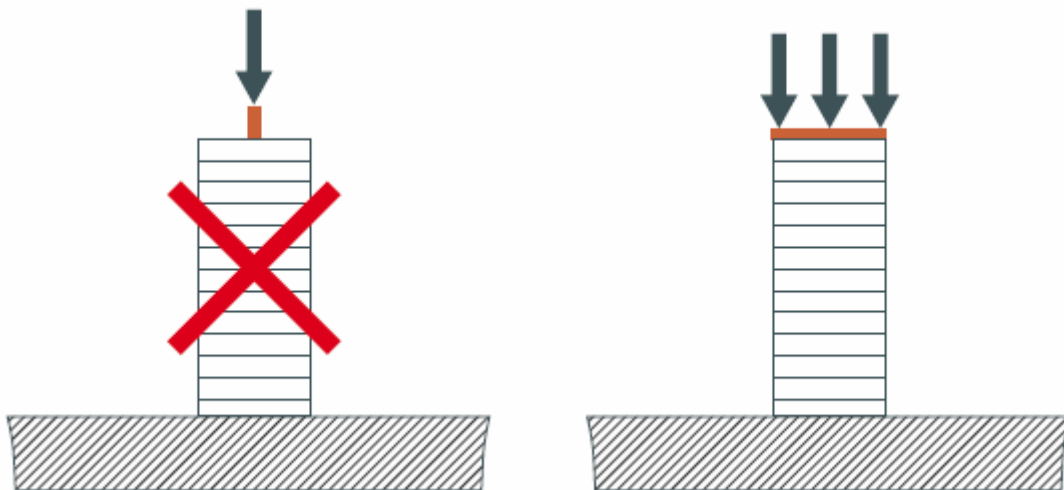
The actuators without preload are sensitive to pulling forces. It is recommended to apply a pre-load in order to optimize the performances of the actuators.



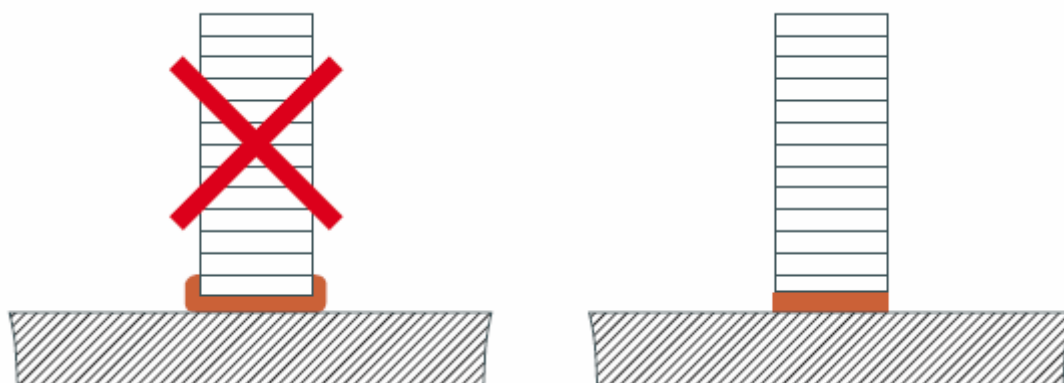
For linear actuators it is recommended not to use a metal plate on top and bottom in order to avoid short circuit.



The force must be applied on the full surface of the actuator in order to assure a good load distribution.



Epoxy glues are well suited for gluing piezoceramics.



WIRES

When you order actuators from Noliac, you can have wires fitted to save time and money. However, you should consider these parameters, when you select a wire for connection:

- Operation voltage
- Intensity of current
- Operating temperature
- Environment for example vacuum

We recommend Teflon wires

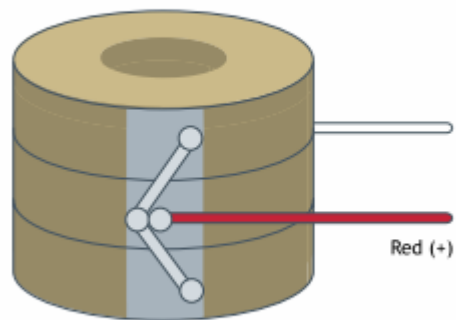
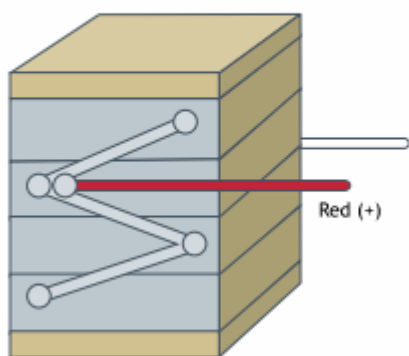
Teflon wires can stand temperatures above 200 °C, whereas PVC wires only resist temperatures up to 80 °C. In tough operating conditions or in vacuum, it is recommended always to use Teflon isolated wire to guarantee the proper performance of PZT-elements.

Wire thickness (AWG)

The wire thickness (AWG) is determined by the current that has to be transmitted to and from the PZT-element. The required current is determined by the capacitance of the PZT-element, the maximum driving frequency and the maximum voltage U_p .

	Option A01	Option A02	Option C
Type	28 AWG Teflon	28 AWG Teflon	Custom
Length	200 +/- 10mm	200 +/- 10mm	To be defined
Position	Middle of the actuator	Middle of the actuator	To be defined
Direction	Perpendicular to the height	Toward top	To be defined

Type A01



Type A02

